

Spherical Tensor Operators

From the previous discussion, it is clear it would be advantageous to give vectors, such as \vec{r} , not in Cartesian component, but in spherical component form. Recalling

$$\begin{pmatrix} rY_{1+1} \\ rY_{10} \\ rY_{1-1} \end{pmatrix} = \sqrt{\frac{3}{4\pi}} \times \begin{pmatrix} -\frac{1}{\sqrt{2}}r \sin \theta e^{+i\phi} \\ r \cos \theta \\ +\frac{1}{\sqrt{2}}r \sin \theta e^{-i\phi} \end{pmatrix} = \sqrt{\frac{3}{4\pi}} \times \begin{pmatrix} -\frac{1}{\sqrt{2}}(x + iy) \\ z \\ +\frac{1}{\sqrt{2}}(x - iy) \end{pmatrix},$$

it will be useful to write the vector \vec{r} in terms of the spherical components (r_{+1}, r_0, r_{-1}) , with

$$r_{+1} = -\frac{1}{\sqrt{2}}(x + iy), \quad r_0 = z, \quad r_{-1} = +\frac{1}{\sqrt{2}}(x - iy). \quad (1)$$

Note, in particular, the differences between r_{+1} and $r_+ = (x + iy)$, and r_{-1} and $r_- = (x - iy)$. Before generalizing this vector result to higher rank tensor components in spherical form, let us look at second rank tensors, T_{ij} , in Cartesian component form. Write the general second rank tensor in terms of a symmetric, traceless part, S_{ij} , an antisymmetric part, A_{ij} , and the trace $\sum_{\alpha} T_{\alpha\alpha}$.

$$\begin{aligned} T_{ij} &= \left(\frac{1}{2}(T_{ij} + T_{ji}) - \frac{1}{3}\delta_{ij} \sum_{\alpha} T_{\alpha\alpha} \right) + \frac{1}{2}(T_{ij} - T_{ji}) + \frac{1}{3}\delta_{ij} \sum_{\alpha} T_{\alpha\alpha} \\ &= S_{ij} + A_{ij} + \frac{1}{3}\delta_{ij} \sum_{\alpha} T_{\alpha\alpha}, \end{aligned} \quad (2)$$

where $S_{ij} = S_{ji}$ and $\sum_{\alpha} S_{\alpha\alpha} = 0$, and $A_{ij} = -A_{ji}$. Under this decomposition of the nine components of the tensor, the 9×9 rotation matrix $O_{ij,\alpha\beta}$ that gives the rotated tensor components T'_{ij} in terms of the original $T_{\alpha\beta}$ via

$$T'_{ij} = \sum_{\alpha,\beta} O_{ij,\alpha\beta} T_{\alpha\beta} \quad (3)$$

will split into three submatrices. The five independent components of the traceless, symmetric tensor, S_{ij} , transform only among themselves. The three components of the antisymmetric tensor, A_{ij} , will transform only among themselves, and the trace of the tensor is a rotationally invariant quantity. The five independent components of S_{ij} transform like the five components of a spherical harmonic, Y_{2m} . The three components of A_{ij} transform like the three components of a vector. We can see this at once if we build the tensor T_{ij} from two vectors (x, y, z) and (X, Y, Z) , with $A_{12} = (xY - yX)$, $A_{31} = (zX - xZ)$, and $A_{23} = (yZ - zY)$, where these are the $z, y,$ and x components of the vector product $\vec{r} \times \vec{R}$. The trace of the tensor transforms like the spherical harmonic Y_{00} . We have thus succeeded in finding second rank tensor components that transform like spherical harmonics, with $l = 2, 1,$ and 0 . As we go to higher rank tensors, this type of decomposition will become more difficult. For example, the 27 components of a third rank tensor will have 10 totally symmetric components. These components could be split further into seven components that transform like spherical harmonics, with $l = 3,$ and three components that transform like the three components of a spherical harmonic, with $l = 1$. A single, totally antisymmetric tensor component exists, which is rotationally invariant; i.e., it transforms like a Y_{00} . The 16 remaining components of mixed symmetry could be split into two sets of five components that transform like spherical harmonics with $l = 2$ and two sets of three components that transform like spherical harmonics, with $l = 1$.

A Definition: Spherical Tensors

The set of $(2k + 1)$ components of a spherical tensor T_q^k with $q = +k, (k - 1), \dots, -k$ and $k = \text{integer or } \frac{1}{2}\text{-integer}$ are a set of $(2k + 1)$ operators that under rotations transform like the components of an angular momentum eigenfunction, ψ_{kq} . Recalling $O_{\text{rot.}} = ROR^{-1}$,

$$(T_q^k)_{\text{rot.}} = R(\alpha, \beta, \gamma)T_q^k R^{-1}(\alpha, \beta, \gamma) = \sum_{v=-k}^k T_v^k D_{vq}^{k*}(\alpha, \beta, \gamma). \tag{4}$$

B Alternative Definition

The components of a spherical tensor can also be defined through their commutator relations with the components of the total angular momentum vector of the system on which the tensor components act. In particular,

$$\begin{aligned} [J_0, T_q^k] &= qT_q^k, \\ [J_{\pm}, T_q^k] &= \sqrt{(k \mp q)(k \pm q + 1)}T_{(q \pm 1)}^k, \end{aligned} \tag{5}$$

where this definition essentially just involves infinitesimal rotation operators in place of the finite rotation operators of eq. (4). Let R correspond to an infinitesimal

rotation about the z, x, y axes. For example, with

$$R = e^{-i\alpha J_z}, \quad \text{and with} \quad \alpha \ll 1, \quad (6)$$

we get

$$\begin{aligned} RT_q^k R^{-1} &= (1 - i\alpha J_z + \dots) T_q^k (1 + i\alpha J_z + \dots) = T_q^k - i\alpha [J_z, T_q^k] + \dots \\ &= \sum_{\nu} D_{\nu q}^{k*} T_q^k = \delta_{\nu q} (1 - i\alpha q + \dots) T_q^k, \end{aligned} \quad (7)$$

where we have used

$$D_{\nu q}^{k*} = \langle k\nu | e^{-i\alpha J_z} | kq \rangle = \delta_{\nu q} (1 - i\alpha q + \dots), \quad (8)$$

thus leading to the first relation, $[J_z, T_q^k] = q T_q^k$. Similarly, combining infinitesimal rotations about the x and y axes, we are lead to the remaining two relations of eq. (5). We can use these relations to show the r_q of eq.(1) are spherical tensor components of rank $k = 1$. We can build higher rank spherical tensors from spherical vectors like these by a build-up process.

C Build-up Process

If $V_{q_1}^{k_1}$ and $U_{q_2}^{k_2}$ are spherical tensors, T_q^k , defined by

$$T_q^k = \sum_{q_1, (q_2)} V_{q_1}^{k_1} U_{q_2}^{k_2} \langle k_1 q_1 k_2 q_2 | kq \rangle, \quad (9)$$

are spherical tensors of rank k . This relation follows from

$$\begin{aligned} RT_q^k R^{-1} &= \sum_{q_1, q_2} R V_{q_1}^{k_1} R^{-1} R U_{q_2}^{k_2} R^{-1} \langle k_1 q_1 k_2 q_2 | kq \rangle \\ &= \sum_{q_1, q_2} \sum_{q'_1, q'_2} V_{q'_1}^{k_1} U_{q'_2}^{k_2} D_{q'_1 q_1}^{k_1*} D_{q'_2 q_2}^{k_2*} \langle k_1 q_1 k_2 q_2 | kq \rangle \\ &= \sum_j \sum_{q'_1, q'_2} V_{q'_1}^{k_1} U_{q'_2}^{k_2} \left(\sum_{q_1, q_2} \langle k_1 q_1 k_2 q_2 | kq \rangle \langle k_1 q_1 k_2 q_2 | j q \rangle \right) \langle k_1 q'_1 k_2 q'_2 | j q' \rangle D_{q'_1 q}^{j*} \\ &= \sum_j \sum_{q'_1, q'_2} V_{q'_1}^{k_1} U_{q'_2}^{k_2} \left(\delta_{jk} \right) \langle k_1 q'_1 k_2 q'_2 | j q' \rangle D_{q'_1 q}^{j*} \\ &= \sum_{q'_1, q'_2} V_{q'_1}^{k_1} U_{q'_2}^{k_2} \langle k_1 q'_1 k_2 q'_2 | kq' \rangle D_{q'_1 q}^{k*} = \sum_{q'} T_{q'}^k D_{q' q}^{k*}. \end{aligned} \quad (10)$$

We shall often also use the shorthand notation

$$T_q^k = \sum_{q_1, (q_2)} V_{q_1}^{k_1} U_{q_2}^{k_2} \langle k_1 q_1 k_2 q_2 | kq \rangle \equiv [V^{k_1} \times U^{k_2}]_q^k. \quad (11)$$

Let us now use this build-up process to construct tensors from two vectors each of spherical rank, $l = 1$. Let us choose the coordinate vector of eq. (1), with $r_q = (r_{+1}, r_0, r_{-1})$, and as our second vector, the momentum vector with spherical

components $p_q = (p_{+1}, p_0, p_{-1})$, and let us construct the spherical tensors

$$T_q^k = \sum_{q_1 q_2} r_{q_1} p_{q_2} \langle 1q_1 1q_2 | kq \rangle, \quad (12)$$

with $k = 0, 1, 2$. With $k = 0$, using

$$\langle 1q_1 1 - q_1 | 00 \rangle = \frac{1}{\sqrt{3}} (-1)^{1-q_1}, \quad (13)$$

we get

$$\begin{aligned} T_0^0 &= -\frac{1}{\sqrt{3}} \sum_q (-1)^q r_{+q} p_{-q} = -\frac{1}{\sqrt{3}} (\vec{r} \cdot \vec{p}) \\ &= -\frac{1}{\sqrt{3}} \left(\frac{1}{2}(x + iy)(p_x - ip_y) + \frac{1}{2}(x - iy)(p_x + ip_y) + zp_z \right). \end{aligned} \quad (14)$$

Note,

$$(\vec{r} \cdot \vec{p}) = \sum_q (-1)^q r_q^1 p_{-q}^1. \quad (15)$$

We can now generalize this scalar product to the more general scalar product of two tensors of rank k ,

$$(T^k \cdot T^k) = \sum_m (-1)^m T_m^k T_{-m}^k. \quad (16)$$

We shall continue by constructing next the coupled spherical tensor operator, constructed from the vectors \vec{r} and \vec{p} to make the spherical tensor of rank $l = 1$,

$$T_q^1 = [r^1 \times p^1]_q^1. \quad (17)$$

$$\begin{aligned} T_{+1}^1 &= \langle 1110 | 11 \rangle r_{+1} p_0 + \langle 1011 | 11 \rangle r_0 p_{+1} \\ &= \frac{1}{\sqrt{2}} r_{+1} p_0 + \left(-\frac{1}{\sqrt{2}}\right) r_0 p_{+1} \\ &= -\frac{1}{2}(x + iy)p_z + \frac{1}{2}z(p_x + ip_y) = \frac{i}{\sqrt{2}} \left(-\frac{1}{\sqrt{2}}(L_x + iL_y) \right). \end{aligned} \quad (18)$$

In general,

$$[r^1 \times p^1]_m^1 = \frac{i}{\sqrt{2}} L_m, \quad \text{with } m = +1, 0, -1. \quad (19)$$

Also, in general,

$$\begin{aligned} [V^1 \times U^1]_{+1}^1 &= \frac{1}{2}(V_0 U_+ - V_+ U_0), \\ [V^1 \times U^1]_0^1 &= -\frac{1}{2\sqrt{2}}(V_+ U_- - V_- U_+), \\ [V^1 \times U^1]_{-1}^1 &= \frac{1}{2}(V_0 U_- - V_- U_0), \end{aligned} \quad (20)$$

where $V_+ = (V_x + iV_y)$, $V_- = (V_x - iV_y)$. Note again the difference from the spherical components $V_{+1} = -\frac{1}{\sqrt{2}}V_+$ and $V_{-1} = +\frac{1}{\sqrt{2}}V_-$. Finally, we build a spherical tensor of rank $l = 2$ from two vectors. The results for the five components are

$$[V^1 \times U^1]_{+2}^2 = \frac{1}{2}V_+ U_+,$$

$$\begin{aligned}
[V^1 \times U^1]_{+1}^2 &= -\frac{1}{2}(V_0U_+ + V_+U_0), \\
[V^1 \times U^1]_0^2 &= -\frac{1}{\sqrt{6}}\left[\frac{1}{2}(V_+U_- + V_-U_+) - 2V_0U_0\right], \\
[V^1 \times U^1]_{-1}^2 &= \frac{1}{2}(V_0U_- + V_-U_0), \\
[V^1 \times U^1]_{-2}^2 &= \frac{1}{2}V_-U_-.
\end{aligned} \tag{21}$$